

A background image shows two young children, a boy on the left and a girl on the right, holding up silver tin cans to their ears as if they are phones. They are connected by a thin horizontal line. The girl is speaking into her can, and the boy is listening. The background is a soft-focus outdoor scene with trees and a building.

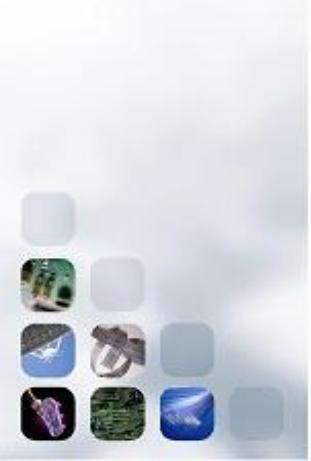
innovating communications

DQMAN Overview

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Weekly Seminar, CTTC.

DQMAN: Background



1992

W. Xu and G. Campbell
(*Illinois Institute of Technology*) → DQRAP
(Cable Television Distribution)

Hybrid protocol based on
distributed queues with near-
optimum performance

2001

Luis Alonso (*UPC*) → DQRAP/CDMA
(3G Mobile Communications)

2005 DQMAN

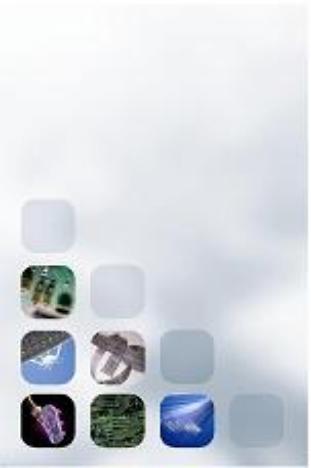
(Distributed Queuing MAC Protocol
for Mobile Ad Hoc Networks)

2005 DQCA for Wireless LAN

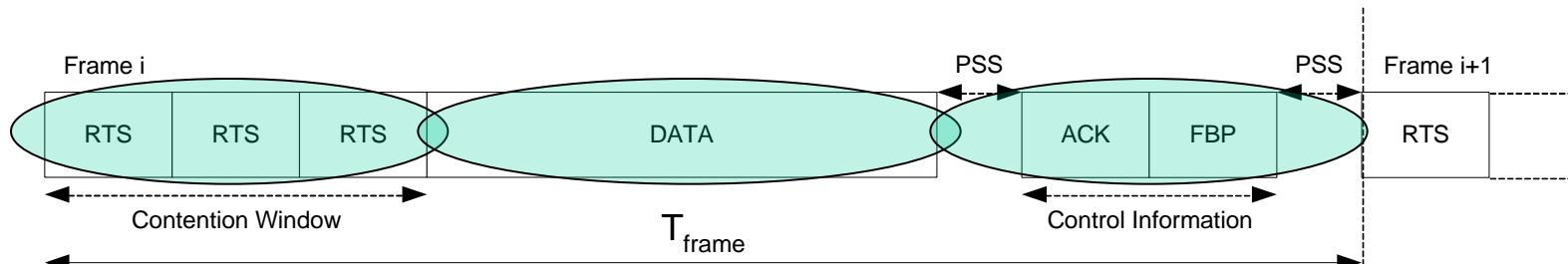
(Distributed Queuing Collision
Avoidance Protocol)

DQMAN: Overview

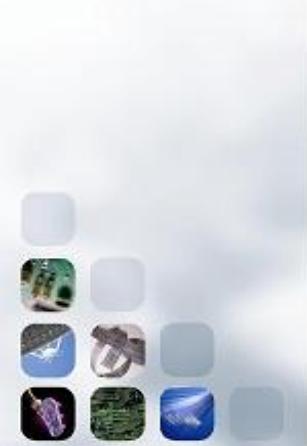
- **Self-organized** MAC protocol for Mobile Ad Hoc NETworkS.
- It implements a MASTER & SLAVE architecture
- Dynamic **self-constructing** algorithm.
- Based on two distributed queues that manage both the **data transmission** and the **resolution of collisions**.
- It does not suffer from instability under all traffic conditions
- Eliminates back-off intervals



DQMAN: Frame structure



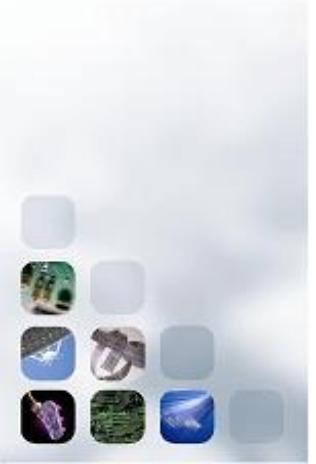
- Special Request to Send Packets (RTS)
 - Known **sequence of chips** that a node with data to transmits sends → minislot selected at random with equal probability
- Data packet
 - Packet with user payload → ideally free of collisions
- Control Information Exchange
 - ACK → from **destination** to **source**
 - FBP → Feed Back Packet **broadcasted by master** node containing the state of the contention minislots, being IDLE, SUCCESS or COLLISION.





DQMAN: *Distributed Queues*

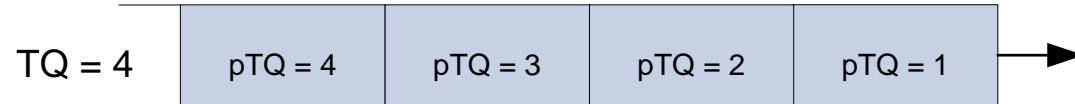
- What do we understand for a **distributed queue**?
- We have a logical queue → that was easy!
- Each node keeps track of the state of the queue
 - Total number of queuing nodes
 - Individual position within the queue
- With the proper control information, all nodes update the state of the queue in a synchronized way
- It is as if “all nodes **share the same queue**”
- **Again, all nodes know:**
 - **Total number of queuing nodes**
 - **Individual position within the queue**



DQMAN: Distributed Queues

- Represented by 4 integer numbers:

TQ // RQ // pTQ // pRQ



Data Transmission Queue (TQ, pTQ)

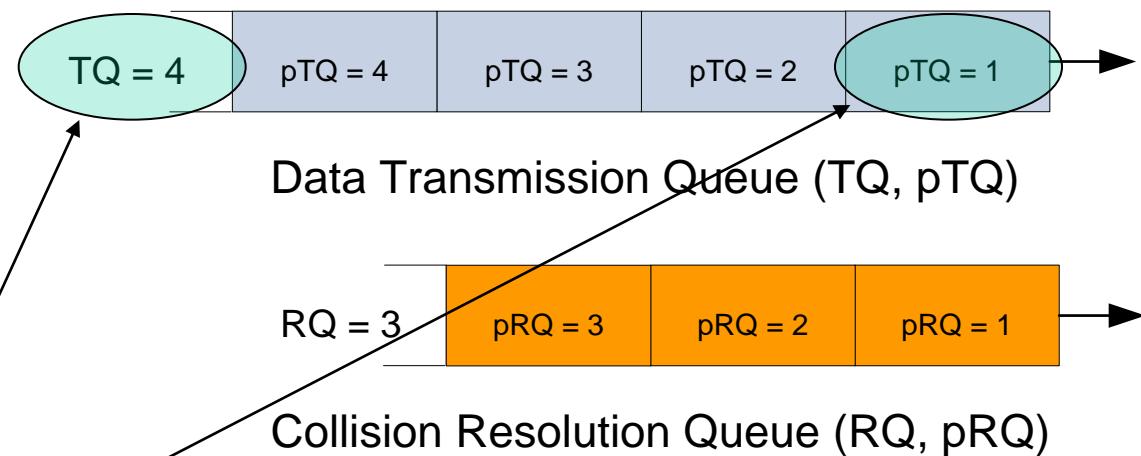


Collision Resolution Queue (RQ, pRQ)

- FBP broadcasted by master node at the end of each frame contains the state of the access mini slots, which is the **only needed information** to update the queues

DQMAN: Distributed Queues

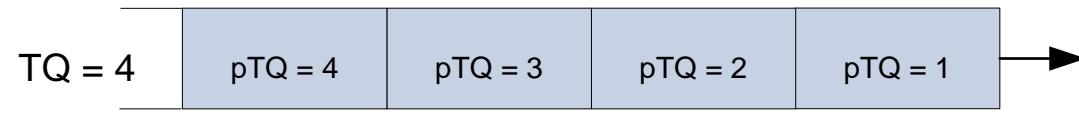
- **Data Transmission Queue (DTQ)**
 - Contains nodes waiting to transmit data because they succeeded in the transmission of the RTS
 - The node in the first position transmits within the next frame



- TQ → total number of nodes queuing at DTQ
- pTQ → individual position of each node at DTQ
 - pTQ has a different value for EACH node

DQMAN: Distributed Queues

- **Collision Resolution Queue (CRQ)**
 - Contains nodes that suffered a RTS collision
 - The nodes in the first position try to resolve their collision within the next frame by sending a new RTS



Data Transmission Queue (TQ, pTQ)

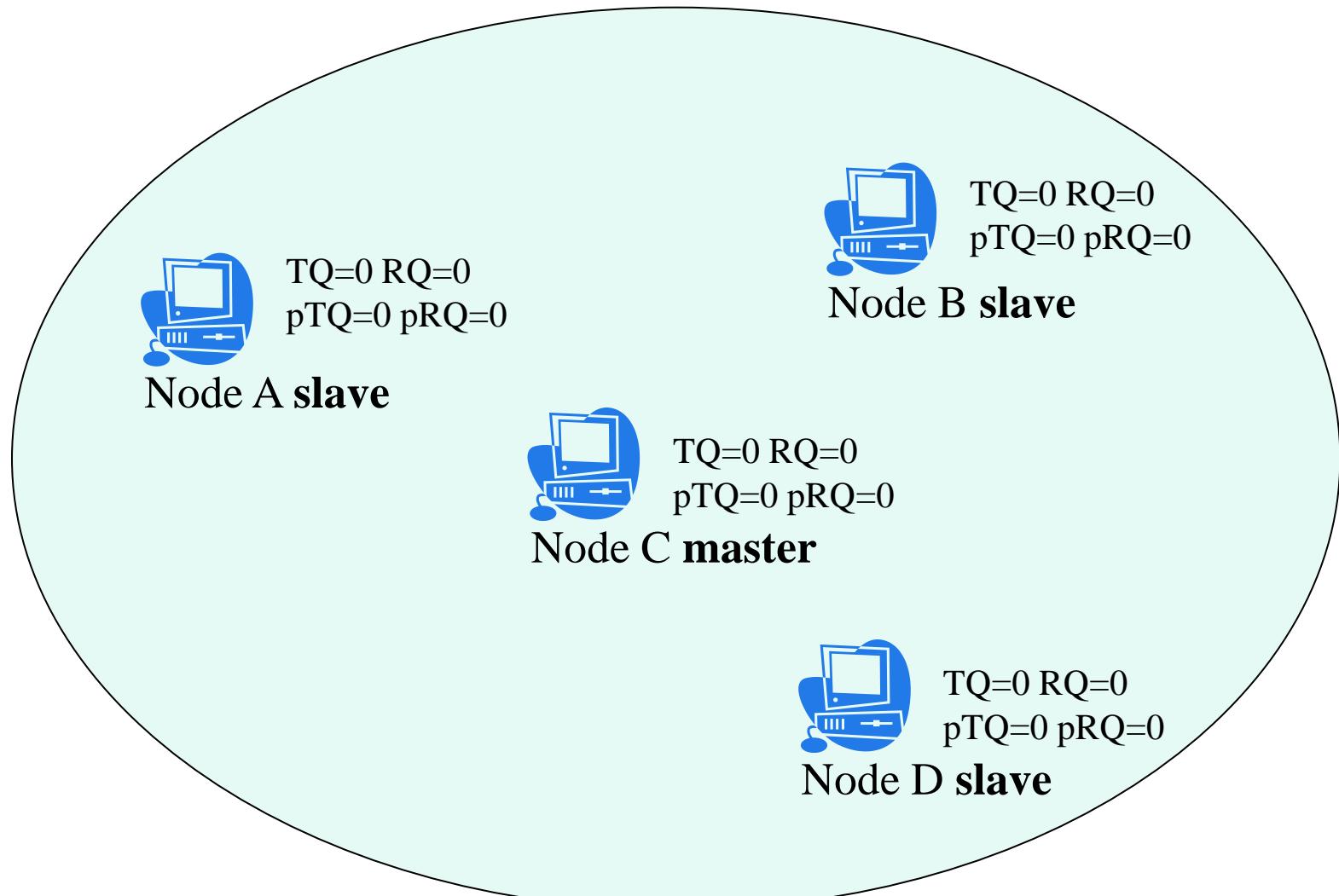


Collision Resolution Queue (RQ, pRQ)

- ~~RQ → total number of nodes queuing at CRQ~~
- ~~pRQ → individual position of each node at CRQ~~
 - **Nodes that collided in the same access minislot have the same value for pRQ!!!**



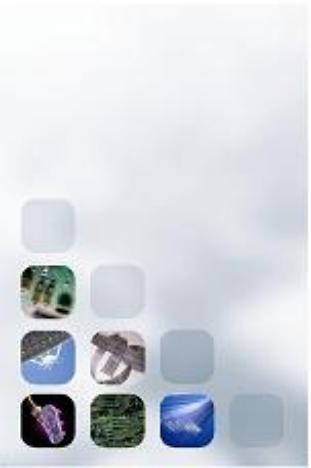
DQMAN: Example



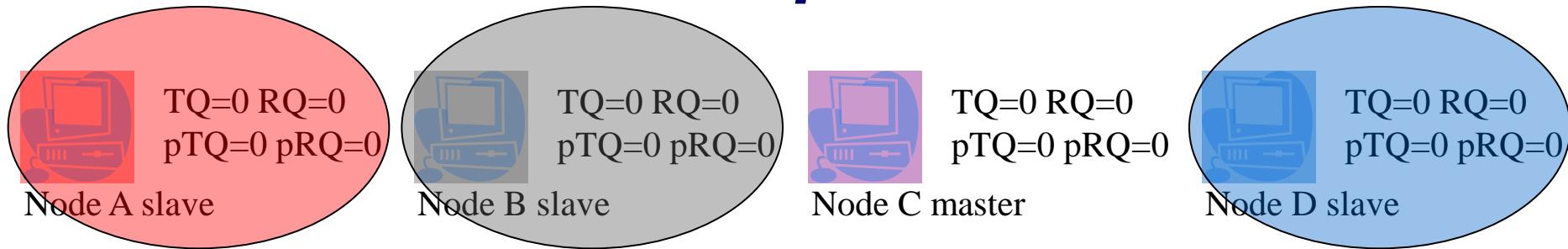
DQMAN: Example



Ending of frame i-1



DQMAN: Example

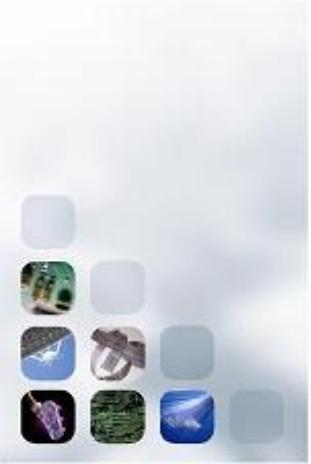


- **DTQ and CRQ are empty**
 - $TQ = 0 \rightarrow$ no nodes waiting to transmit
 - $RQ = 0 \rightarrow$ no nodes waiting to solve a collision
 - $pTQ = 0$ and $pRQ = 0$ for all nodes
- **Nodes A, B and D have to transmit**
- **They select AT RANDOM an access minislot to send and RTS**
 - Node A selects minislot 1
 - Node B selects minislot 3
 - Node D selects minislot 1 \rightarrow A and D WILL COLLIDE!

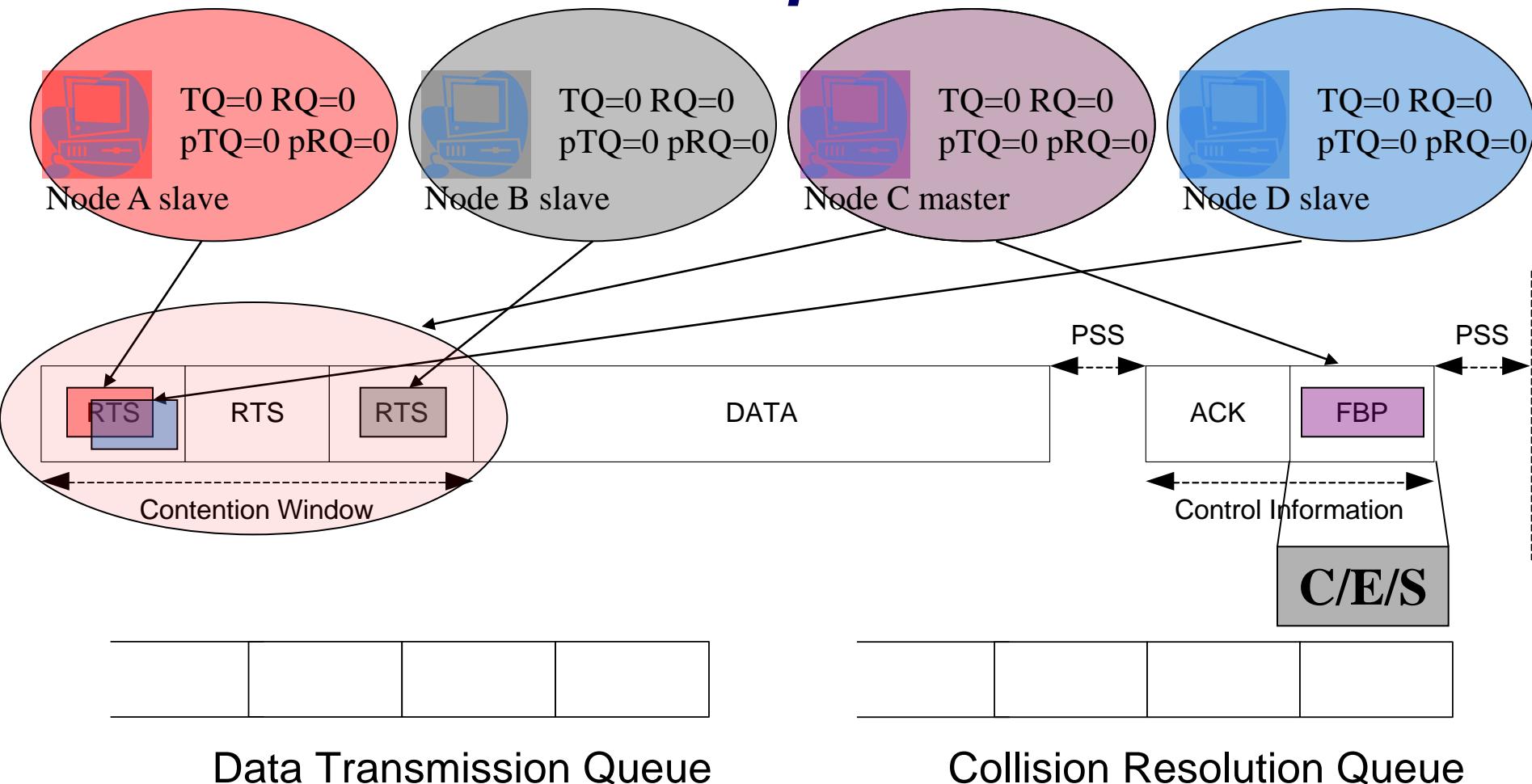
DQMAN: Example



Beginning of frame i

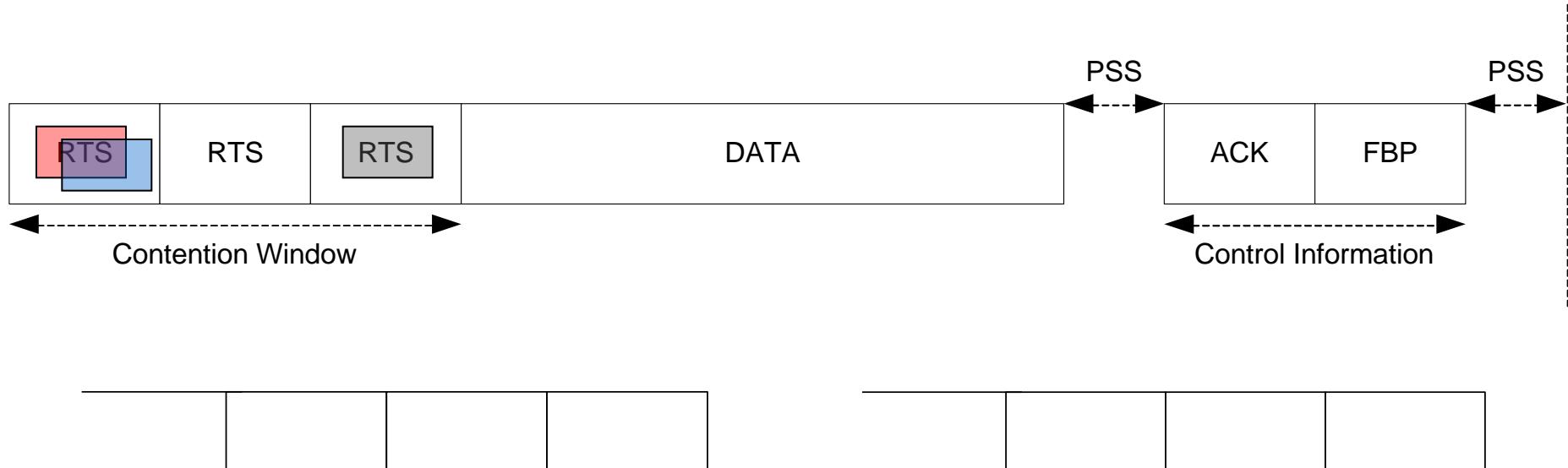
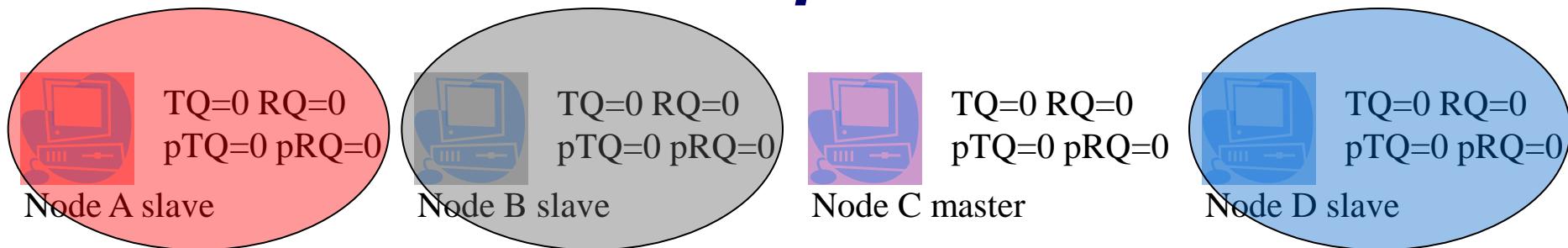


DQMAN: Example



Current Frame = i

DQMAN: Example



Data Transmission Queue

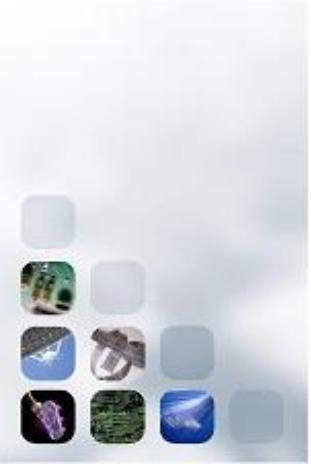
Collision Resolution Queue

Ending of Current Frame = $i \rightarrow$ Nodes execute protocol rules with FBP information

DQMAN: Example



Ending of frame i



DQMAN: Example



Node A slave

TQ=1 RQ=1
pTQ=0 pRQ=1



Node B slave

TQ=1 RQ=1
pTQ=1 pRQ=0



Node C master

TQ=1 RQ=1
pTQ=0 pRQ=0



Node D slave

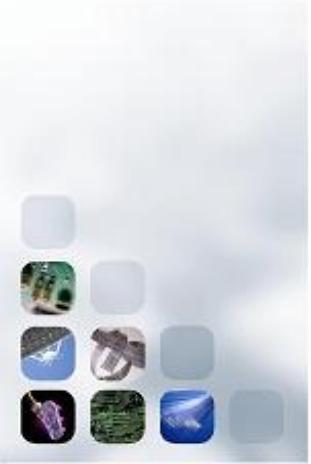
TQ=1 RQ=1
pTQ=0 pRQ=1

- **Node B succeeded → pTQ =1**
 - Node B will transmit data in the next frame
- **Nodes A and D collided in their access request**
 - They enter CRQ
 - They are in the first position, i.e. pRQ=1 for both
 - They try to solve the collision in the following frame
 - They reselect AT RANDOM an access minislot
 - Node A selects minislot 2
 - Node D selects minislot 1
 - THEY WILL SUCCEED!

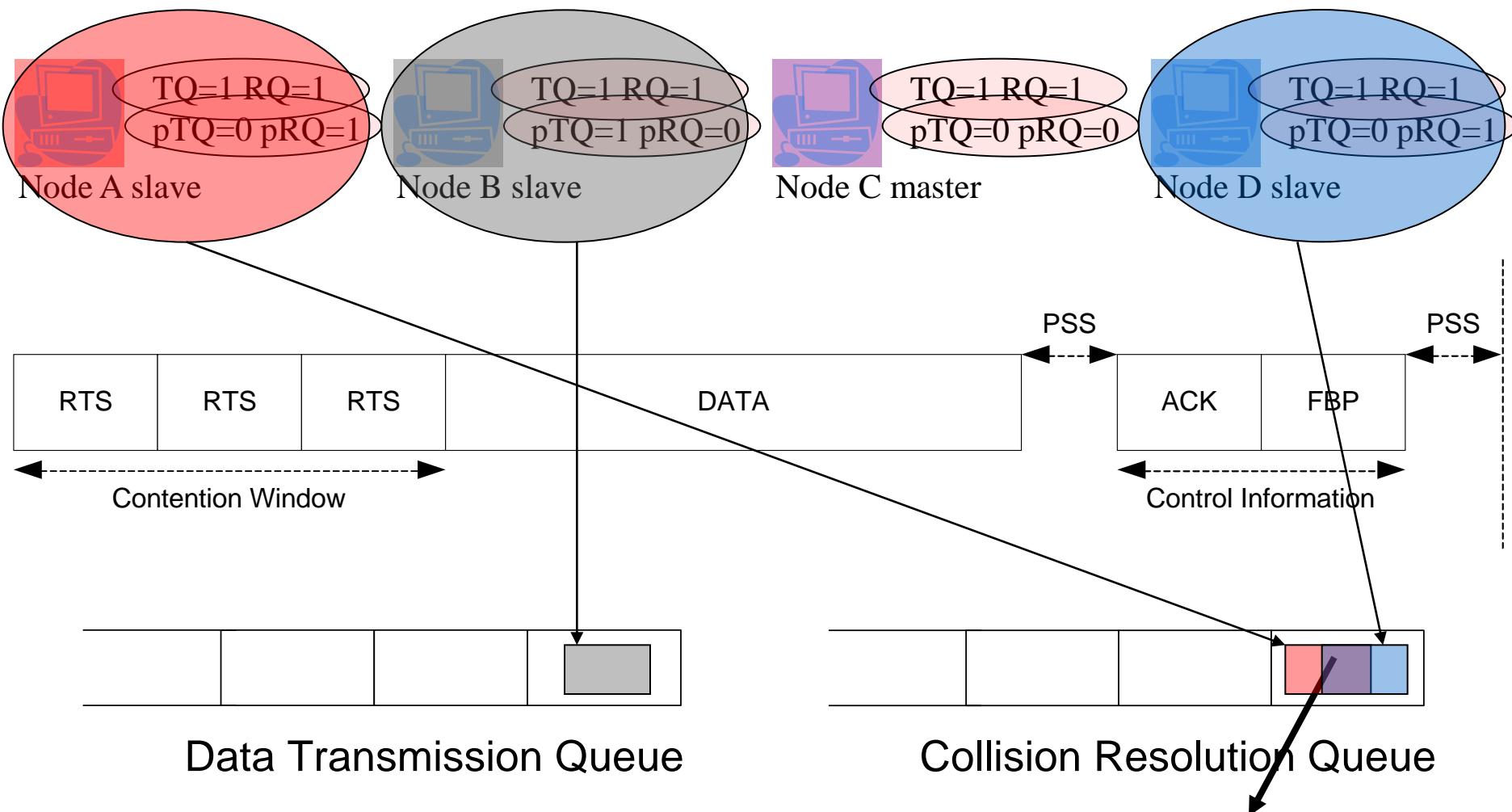
DQMAN: Example



Beginning of frame $i+1$



DQMAN: Example

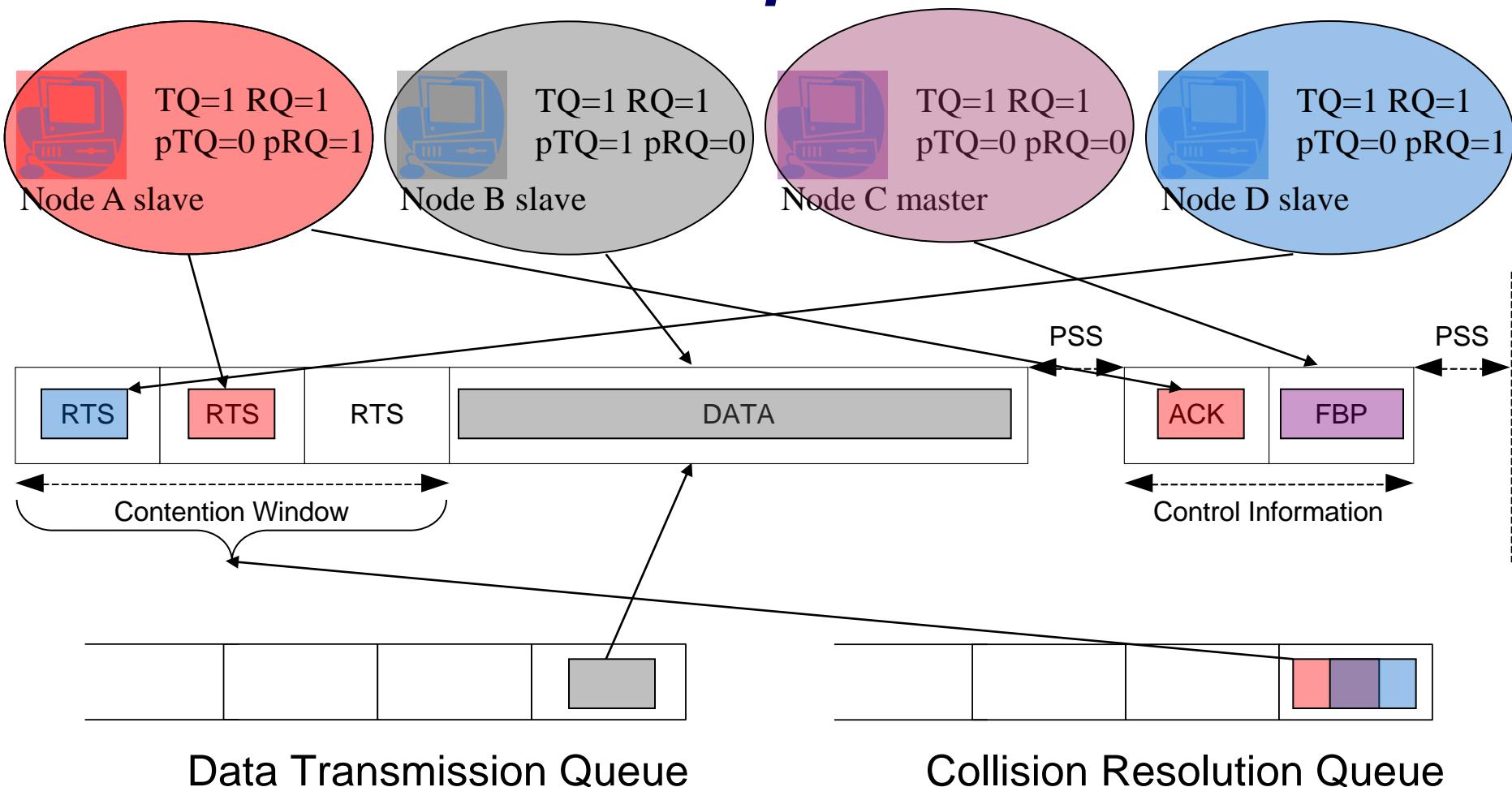


Current Frame = $i + 1$



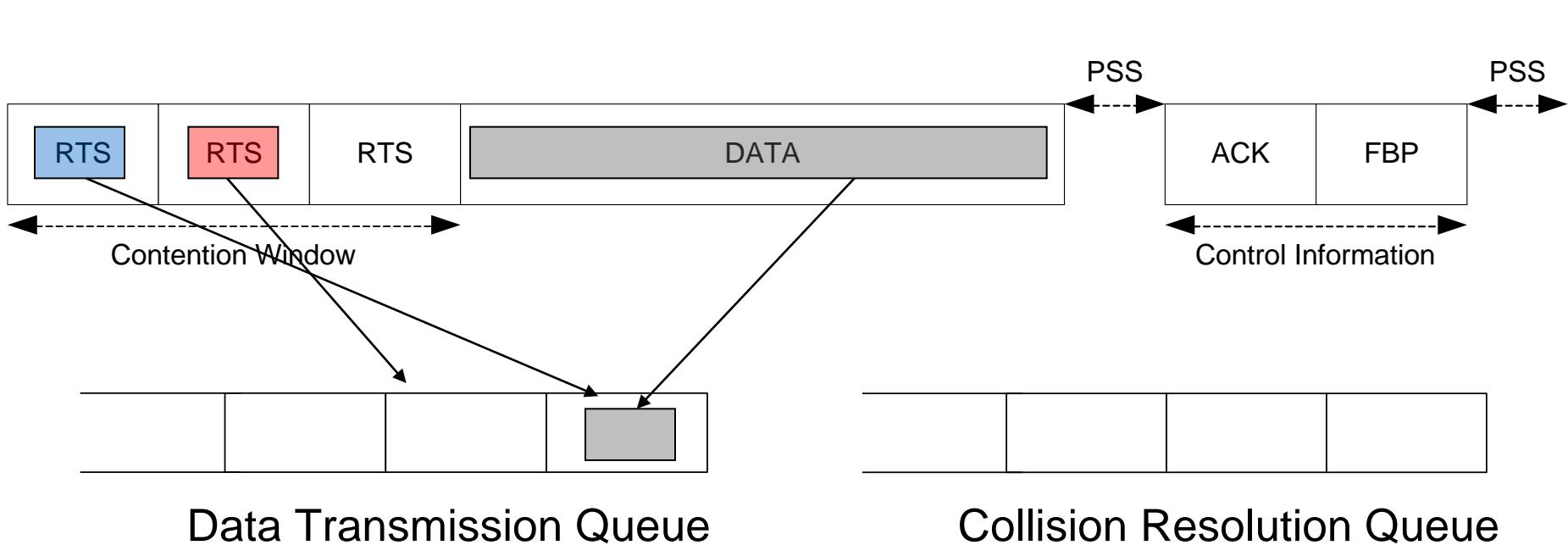
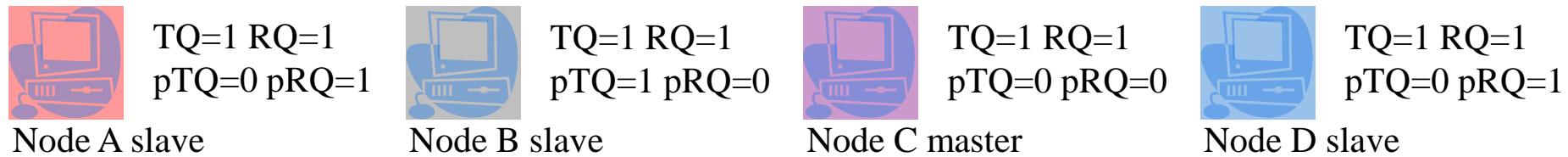
New Access Channel
Requests Forbidden

DQMAN: Example



Current Frame = $i + 1$

DQMAN: Example



Current Frame = $i + 1$



Thanks for your kind attention!

- Questions?



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