

A background image shows two young children, a boy on the left and a girl on the right, holding up silver tin cans to their ears as if they are phones. They are connected by a thin horizontal line. The girl is speaking into her can, and the boy is listening. The background is a soft-focus outdoor scene with trees and a building.

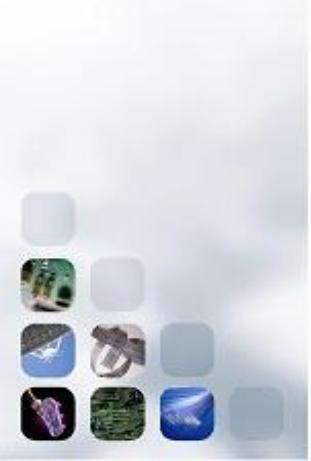
innovating communications

## DQMAN Overview

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*Research Associate*  
**CTTC**

*Weekly Seminar, CTTC.*

# DQMAN: Background



1992

W. Xu and G. Campbell  
(*Illinois Institute of Technology*) → DQRAP  
(Cable Television Distribution)

Hybrid protocol based on  
distributed queues with near-  
optimum performance

2001

Luis Alonso (*UPC*) → DQRAP/CDMA  
(3G Mobile Communications)

2005 DQMAN

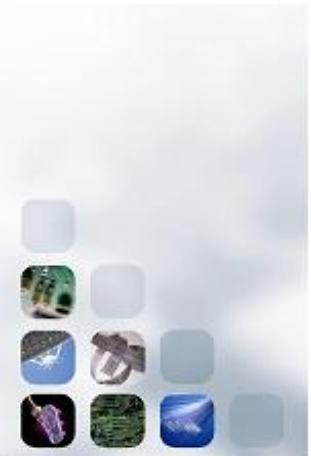
(Distributed Queuing MAC Protocol  
for Mobile Ad Hoc Networks)

2005 DQCA for Wireless LAN

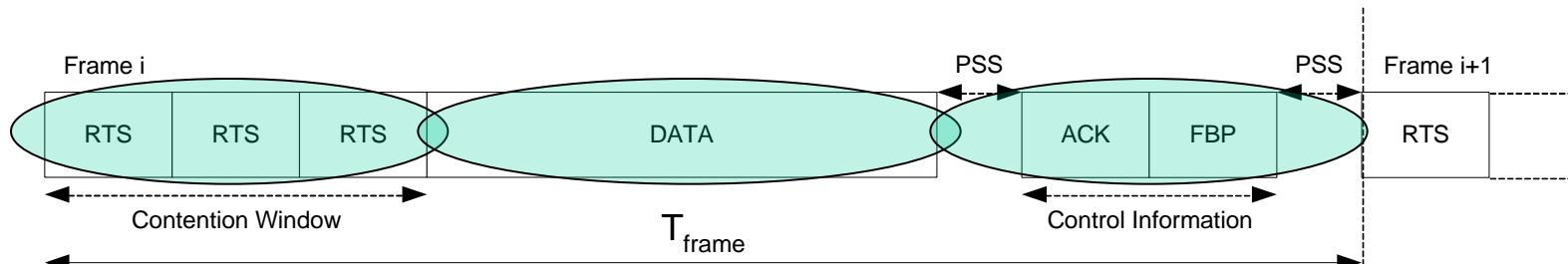
(Distributed Queuing Collision  
Avoidance Protocol)

# DQMAN: Overview

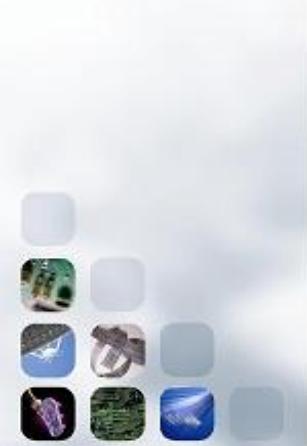
- **Self-organized** MAC protocol for Mobile Ad Hoc NETworkS.
- It implements a MASTER & SLAVE architecture
- Dynamic **self-constructing** algorithm.
- Based on two distributed queues that manage both the **data transmission** and the **resolution of collisions**.
- It does not suffer from instability under all traffic conditions
- Eliminates back-off intervals



# DQMAN: Frame structure



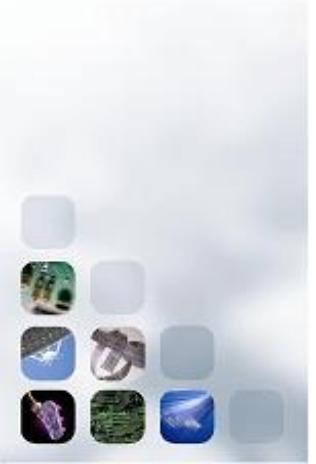
- Special Request to Send Packets (RTS)
  - Known **sequence of chips** that a node with data to transmits sends → minislot selected at random with equal probability
- Data packet
  - Packet with user payload → ideally free of collisions
- Control Information Exchange
  - ACK → from **destination** to **source**
  - FBP → Feed Back Packet **broadcasted by master** node containing the state of the contention minislots, being IDLE, SUCCESS or COLLISION.





# DQMAN: *Distributed Queues*

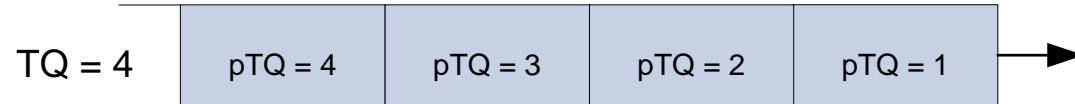
- What do we understand for a **distributed queue**?
- We have a logical queue → that was easy!
- Each node keeps track of the state of the queue
  - Total number of queuing nodes
  - Individual position within the queue
- With the proper control information, all nodes update the state of the queue in a synchronized way
- It is as if “all nodes **share the same queue**”
- **Again, all nodes know:**
  - **Total number of queuing nodes**
  - **Individual position within the queue**



# DQMAN: Distributed Queues

- Represented by 4 integer numbers:

**TQ // RQ // pTQ // pRQ**



Data Transmission Queue (TQ, pTQ)

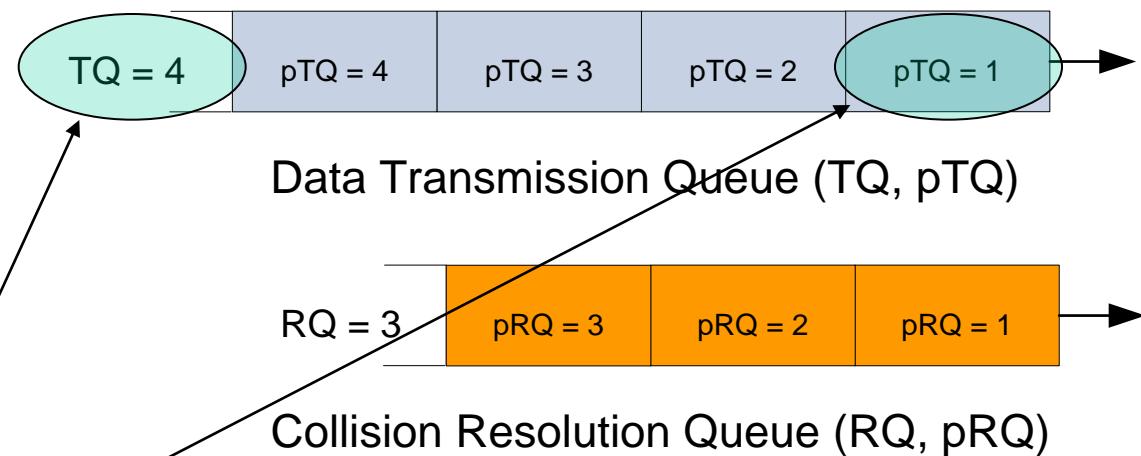


Collision Resolution Queue (RQ, pRQ)

- FBP broadcasted by master node at the end of each frame contains the state of the access mini slots, which is the **only needed information** to update the queues

# DQMAN: Distributed Queues

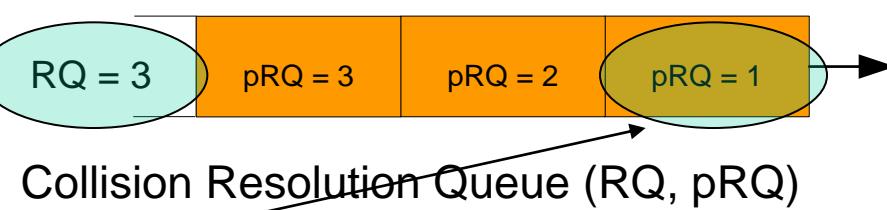
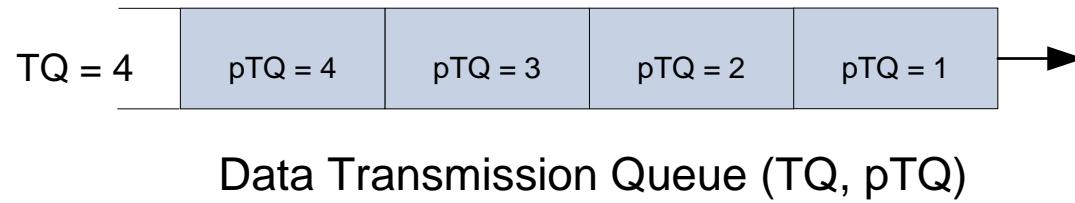
- **Data Transmission Queue (DTQ)**
  - Contains nodes waiting to transmit data because they succeeded in the transmission of the RTS
  - The node in the first position transmits within the next frame



- TQ → total number of nodes queuing at DTQ
- pTQ → individual position of each node at DTQ
  - **pTQ has a different value for EACH node**

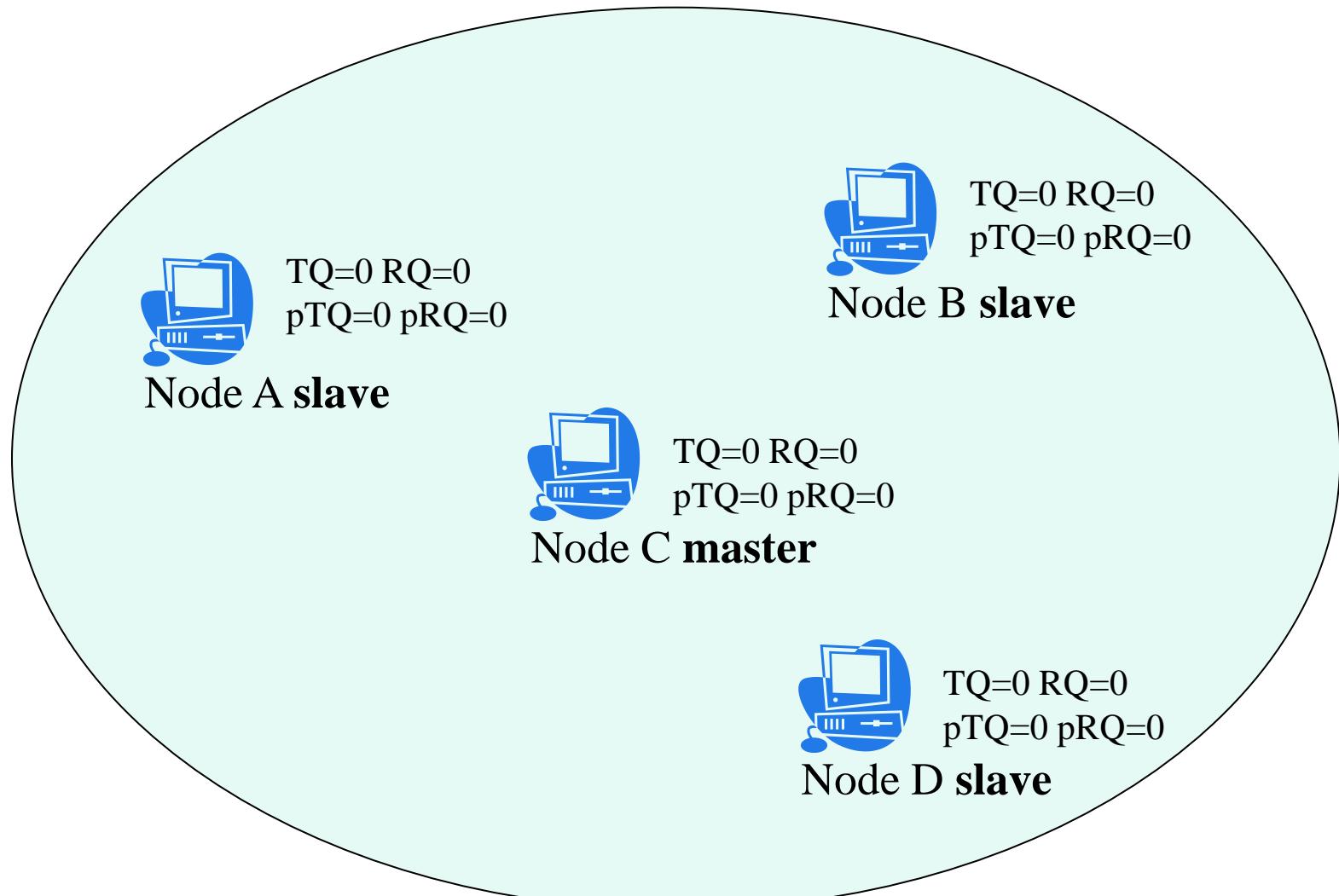
# DQMAN: Distributed Queues

- **Collision Resolution Queue (CRQ)**
  - Contains nodes that suffered a RTS collision
  - The nodes in the first position try to resolve their collision within the next frame by sending a new RTS



- ~~$RQ \rightarrow$  total number of nodes queuing at CRQ~~
- $pRQ \rightarrow$  individual position of each node at CRQ
  - Nodes that collided in the same access minislot have the same value for pRQ!!!

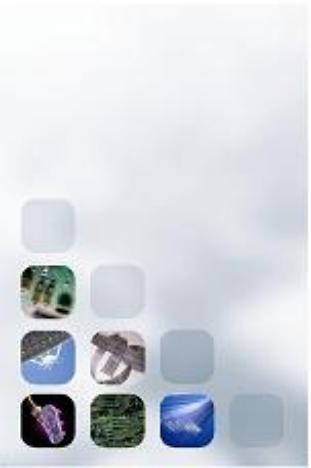
# DQMAN: Example



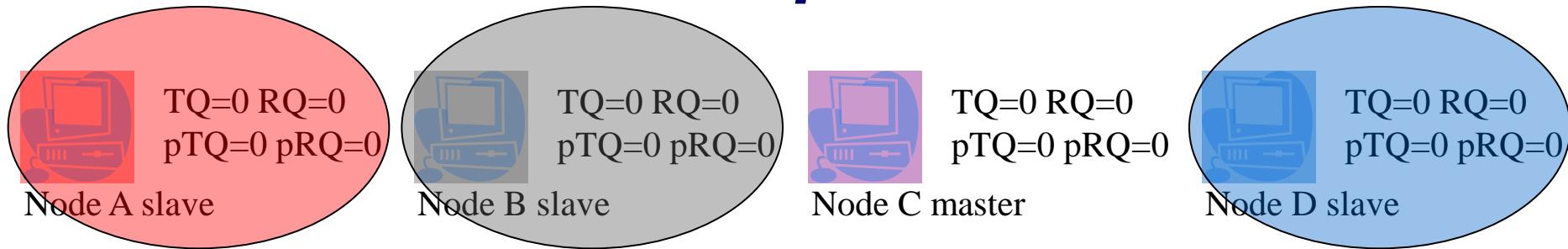
## DQMAN: Example



# Ending of frame i-1



# DQMAN: Example

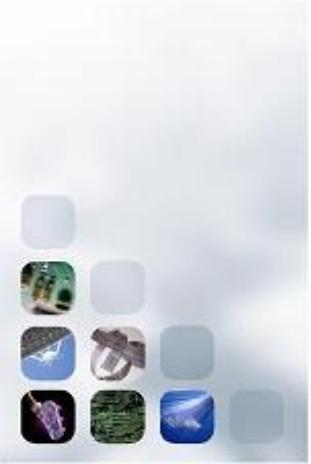


- **DTQ and CRQ are empty**
  - $TQ = 0 \rightarrow$  no nodes waiting to transmit
  - $RQ = 0 \rightarrow$  no nodes waiting to solve a collision
  - $pTQ = 0$  and  $pRQ = 0$  for all nodes
- **Nodes A, B and D have to transmit**
- **They select AT RANDOM an access minislot to send and RTS**
  - Node A selects minislot 1
  - Node B selects minislot 3
  - Node D selects minislot 1  $\rightarrow$  A and D WILL COLLIDE!

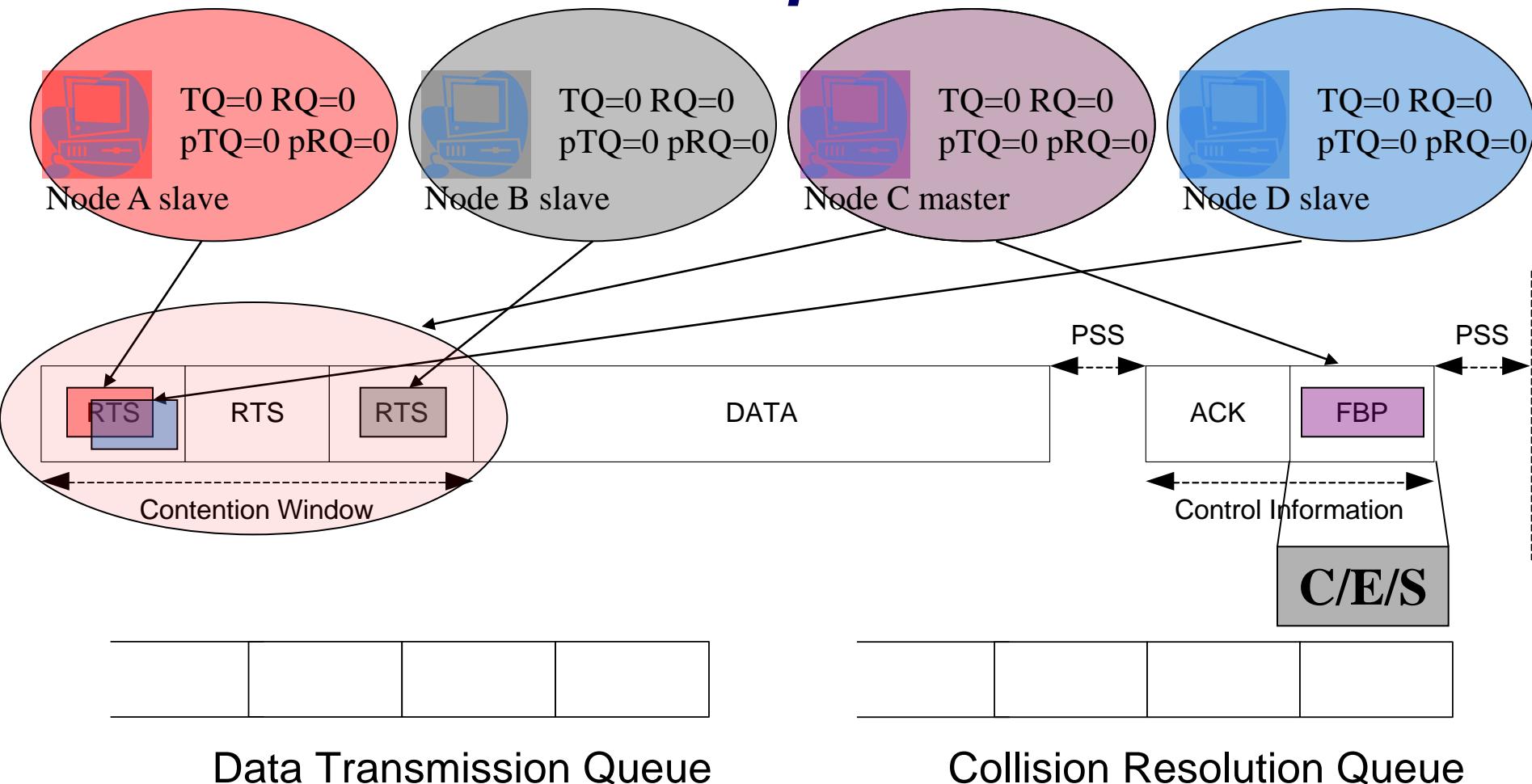
## *DQMAN: Example*



# Beginning of frame i

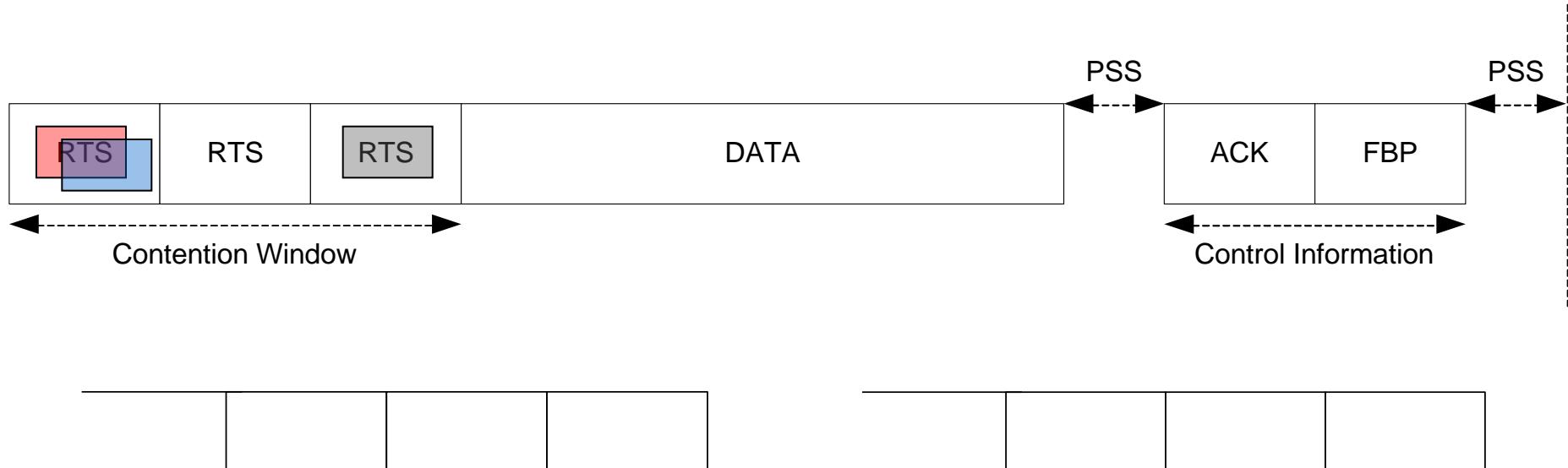
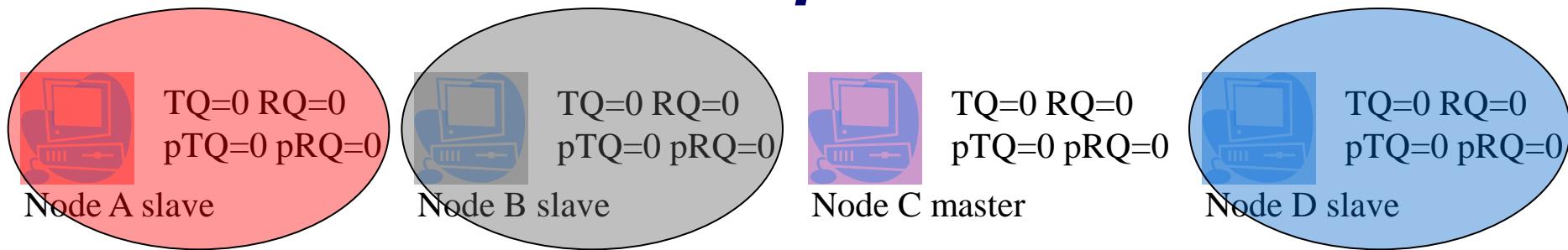


# DQMAN: Example



**Current Frame = i**

# DQMAN: Example

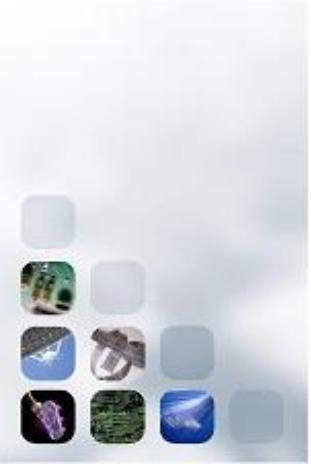


***Ending of Current Frame =  $i \rightarrow$  Nodes execute protocol rules with FBP information***

## DQMAN: Example



# Ending of frame i



# **DQMAN: Example**



Node A slave

TQ=1 RQ=1  
pTQ=0 pRQ=1



Node B slave

TQ=1 RQ=1  
pTQ=1 pRQ=0



Node C master

TQ=1 RQ=1  
pTQ=0 pRQ=0



Node D slave

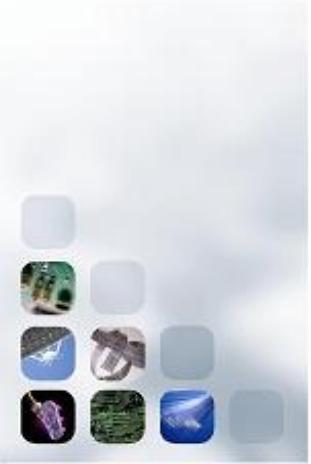
TQ=1 RQ=1  
pTQ=0 pRQ=1

- **Node B succeeded → pTQ =1**
  - Node B will transmit data in the next frame
- **Nodes A and D collided in their access request**
  - They enter CRQ
  - They are in the first position, i.e. pRQ=1 for both
  - They try to solve the collision in the following frame
  - They reselect AT RANDOM an access minislot
    - Node A selects minislot 2
    - Node D selects minislot 1
    - THEY WILL SUCCEED!

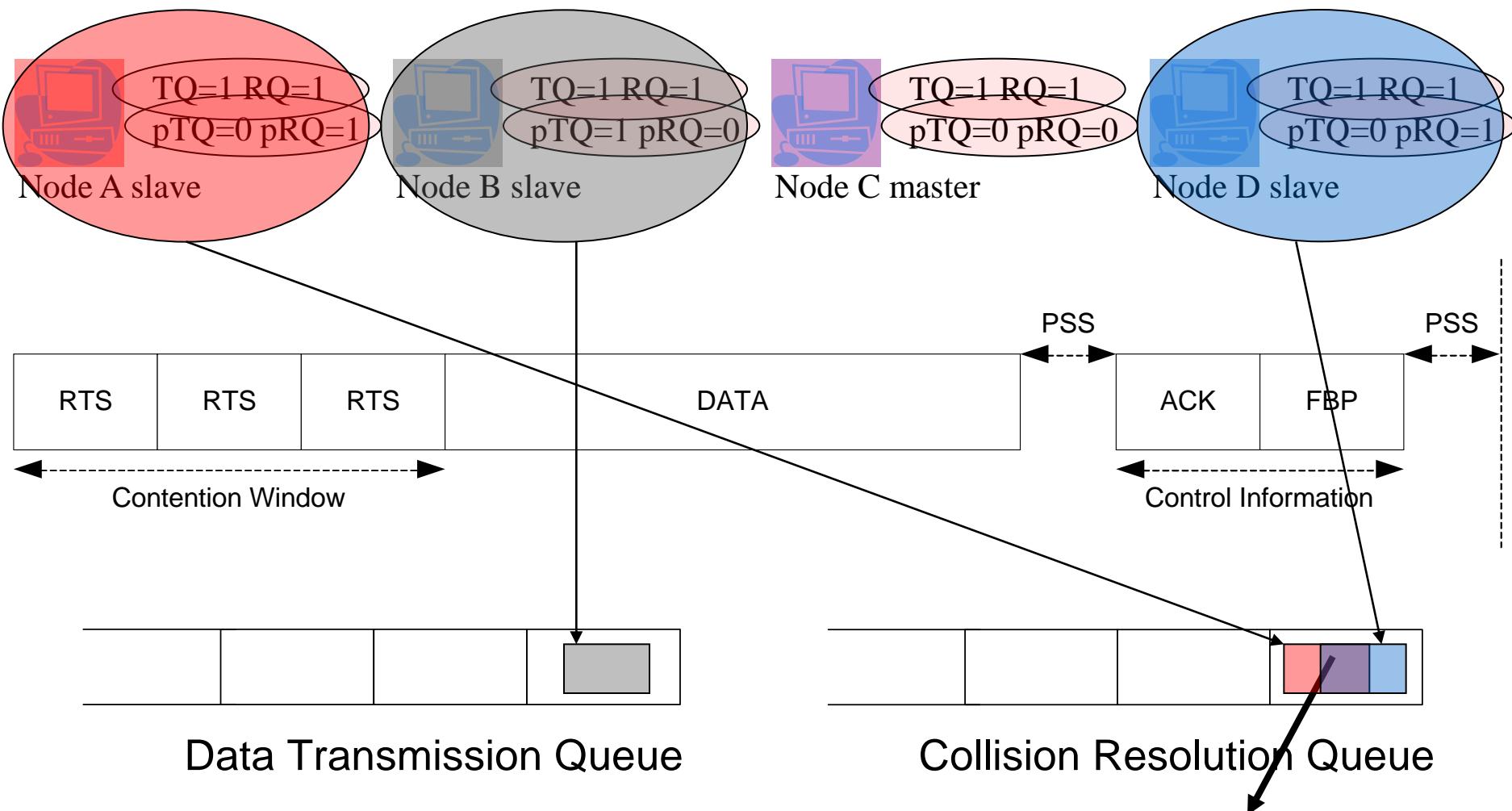
## DQMAN: Example



# Beginning of frame $i+1$



# DQMAN: Example

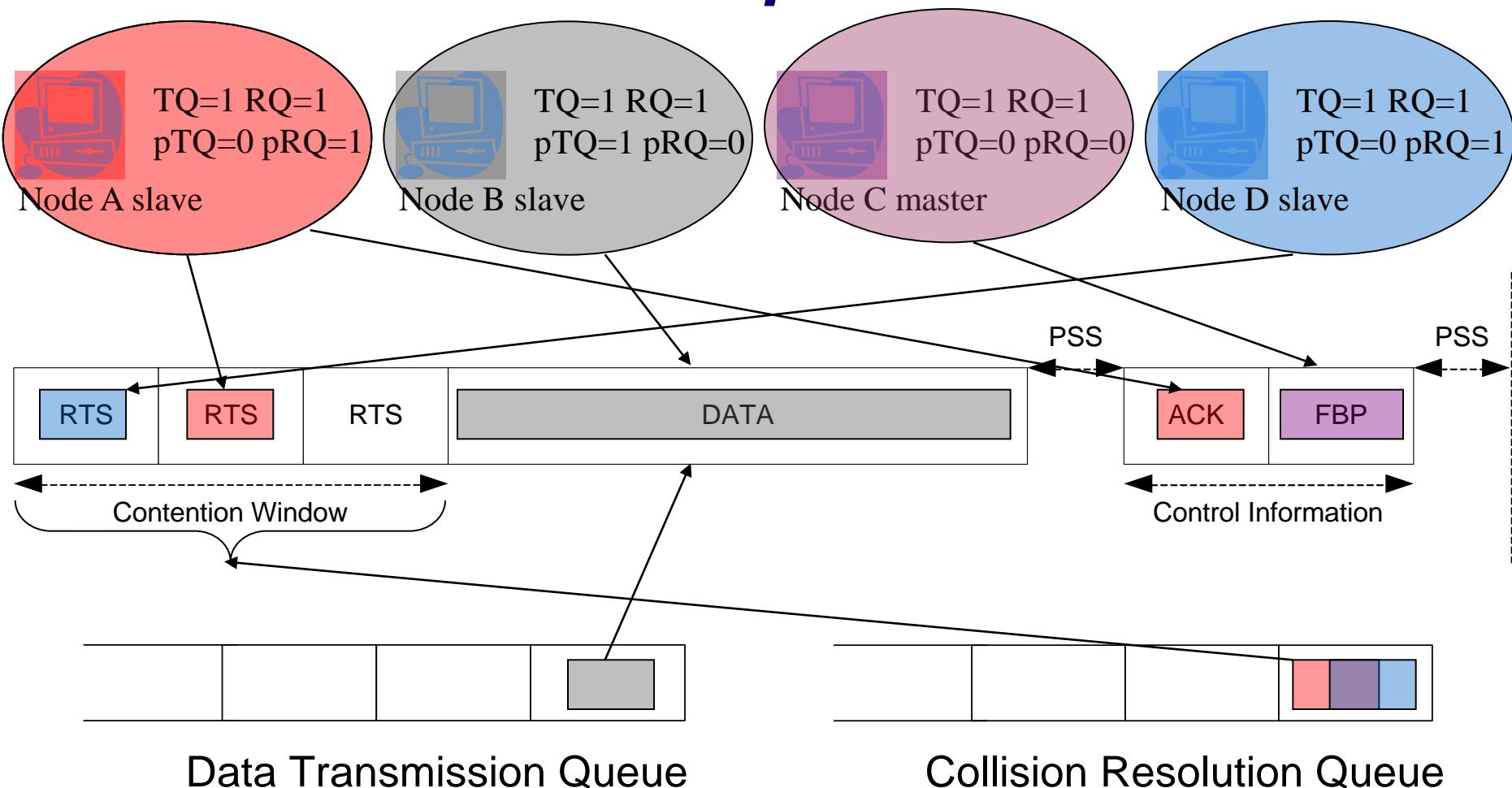


**Current Frame =  $i + 1$**



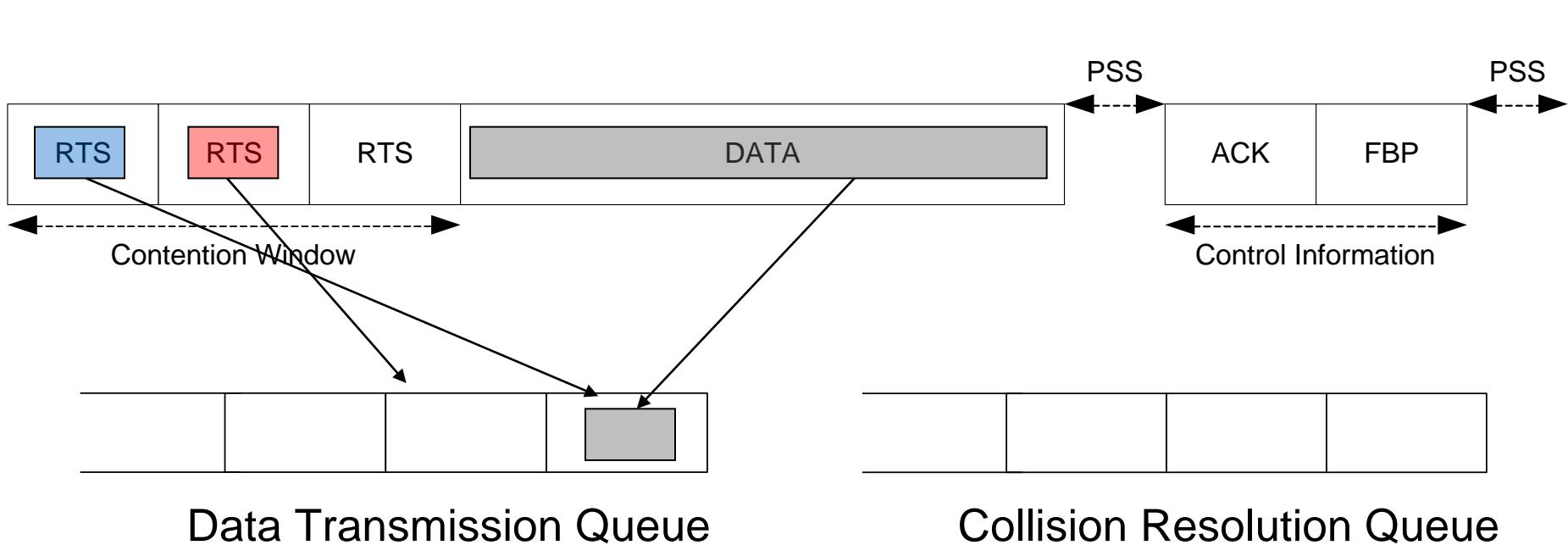
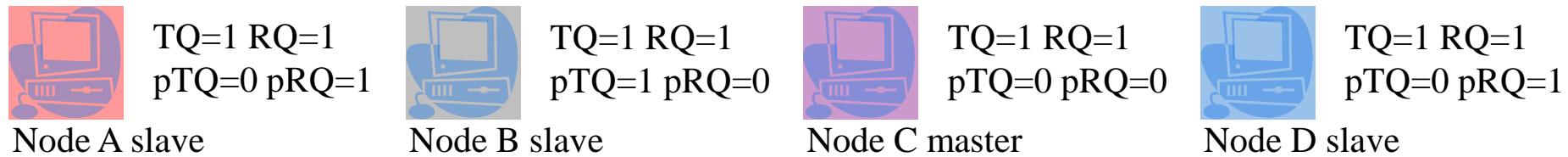
New Access Channel  
Requests Forbidden

# DQMAN: Example



**Current Frame =  $i + 1$**

# DQMAN: Example



**Current Frame =  $i + 1$**



# *Thanks for your kind attention!*

- Questions?



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