

R2 Installation Guides

In R2 the installation procedure is identical to that in R1 as defined in detail in [R1 Installation Guides](#)

Rover Blueprint

The Rover blueprint installation procedure and input file is identical to that in R1. Refer to the detailed installation guide for Rover in R1 here [Rover Deployment](#).

Unicycle Blueprints

Due to the upgrade to Airship 1.3 minor changes to the site specific input yaml files for the Unicycle blueprints has been necessary.

The modifications to the Unicycle pod input files are shown in the following example configuration files:

- [R2 Example Configuration Input Files - Unicycle Pods with OVS-DPDK Dataplane on Dell 740XD Servers](#)
- [R2 Example Configuration Input File - Unicycle Pods with SR-IOV Dataplane on Dell 740XD Servers](#)

The files are selected in the same way as they were in R1 shown here [Unicycle Site Input File Selection](#)