

I-VICS R5 Release Notes

Release Notes for the I-VICS Blue Print

- Summary

what is released

- Create BluVal running environment
 - Create automatic test scrip
- Dependencies of the release (upstream version, patches)

These packages were released:

- autoware_auto_algorithm
 - autoware_auto_cmake
 - autoware_auto_create_pkg
 - autoware_auto_examples
 - autoware_auto_geometry
 - autoware_auto_helper_functions
 - autoware_auto_msgs
 - euclidean_cluster
 - euclidean_cluster_nodes
 - hungarian_assigner
 - kalman_filter
 - lidar_utils
 - localization_common
 - localization_nodes
 - motion_model
 - ndt
 - optimization
 - point_cloud_fusion
 - ray_ground_classifier
 - ray_ground_classifier_nodes
 - serial_driver
 - velodyne_driver
 - velodyne_node
 - voxel_grid
 - voxel_grid_nodes
- differences from previous version

- Upgrade Procedures

- N/A

- Release Data

- Module version changes

- V1.0.0

- Document Version Changes

- N/A

- Software Deliverable

- Software is available in the ai edge repo: <https://autwarefoundation.gitlab.io/autoware.auto/AutowareAuto/installation-ade.html>

- Fixed Issues and Bugs

- N/A

- Known Limitations, Issues and Workarounds

- References

- <https://nexus.akraino.org/content/sites/logs/fate/job/I-VICS/5/>