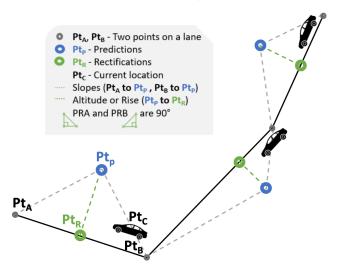
Documentation - R6 (MEC-based)

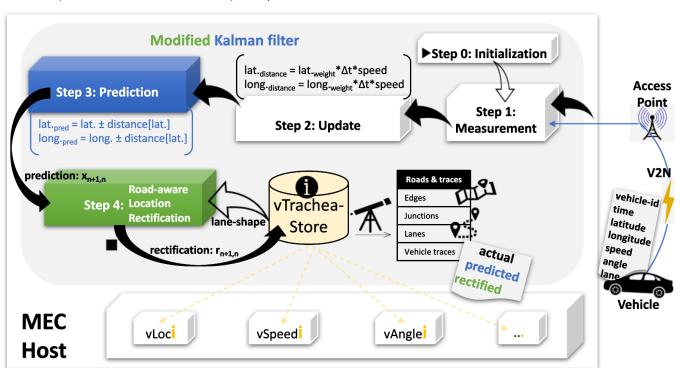
This section contains the documentation related to release 6 of this blueprint.

Expand all Collapse all

The Road-aware Location Rectification process/feature has been introduced/developed/added to the blueprint. Figure of its process is shown as follows:



The internal procedure of Modified Kalman Filter is pictorially described as:



The vTrachea-store is as follows. Its schema is shown below. It shows the relationship between vehicular entities (vehicles, their traces) and road structural entities (roads, lanes, junctions). The figure is self-explanatory, and is as follows:

